Introduction to Lattices

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Contents

1 Lattices in \mathbb{R}^m

2 The LLL Algorithm

3 Babai's Nearest Plane Algorithm

4 Complexity Results

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Algebraic Algorithms



- Algebraic Algorithms
- Combinatorial Optimization

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Complexity

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- Complexity
- Cryptanalysis

- Algebraic Algorithms
- Combinatorial Optimization
- Complexity
- Cryptanalysis
- Cryptography
 - Very efficient
 - Worst case security guarantees

- No known quantum attacks
- Exotic constructions

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Definition

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Given *n* linearly independent vectors $b_1, \ldots, b_n \in \mathbb{R}^m$ the lattice generated by them is the set

$$\mathcal{L}(b_1,\ldots,b_n) = \{\sum_{i=1}^n x_i b_i \mid x_i \in \mathbb{Z}\}$$

Denoting $B = [b_1 \ b_2 \ \dots \ b_n]$ equivalently we have

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- B is the basis of the lattice.
- *m* is its dimension.
- n is its rank.
- A lattice is full rank if m = n.
- The span of the lattice is the linear span of its basis.

- A lattice has many (infinite) equivalent bases.
- We next define the fundamental parallilepiped with respect to a basis *B*.

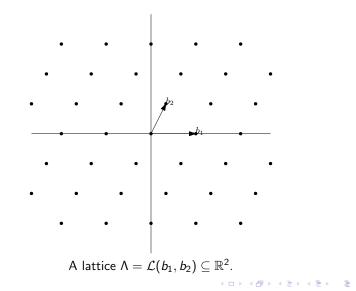
Definition

Fundamental Parallilepiped For a basis ${\cal B}$ the fundamental parallilepiped is the set

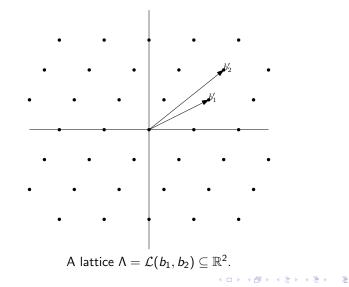
$$\mathcal{P}(B) = \{Bx \mid x \in [0,1)\}$$

Placing a copy of $\mathcal{P}(B)$ in every lattice point we partition span(B).

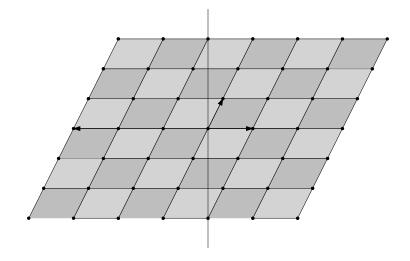
A Lattice in \mathbb{R}^2



A different basis for the same lattice

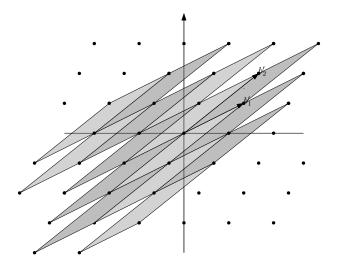


Fundamental Parallilepiped I



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Fundamental Parallilepiped II



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Lemma

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 Suppose $x \in \mathcal{P}(b_1, \ldots, b_n) \cap \Lambda = \{0\}$. Then

x = Bz for $z \in \mathbb{Z}^n$

$$x = By$$
 for $y \in [0, 1)^n$

Since b_1, \ldots, b_n are linearly independent we get z = 0.

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Since $b_1, ..., b_n$ are linearly independent we get $z = 0$
(⇐) Suppose $x \in \Lambda$. Then $x = By$ for $y \in \mathbb{R}^n$. Now
 $x' = B(y - |y|) \in \Lambda$. We get that $y = |y|$.

Lemma

Suppose $B, D \in \mathbb{R}^{m \times n}$ rank n matrices. Then $\mathcal{L}(B) = \mathcal{L}(D)$ iff D = BU for $U \in \mathbb{Z}^{n \times n}$ unimodular matrix.

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Another characterizations for equivalent basis is the following: B, D are equivalent basis iff we can constract D from B with the following operations

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3 $b_i \leftarrow -b_i$

Determinant of a Lattice

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The determinant of a lattice Λ is the *n*-dimentional volume of a fundamental parallepiped $\mathcal{P}(B)$, that is det $(\Lambda) = \sqrt{\det(B^T B)}$.

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Determinant of a Lattice

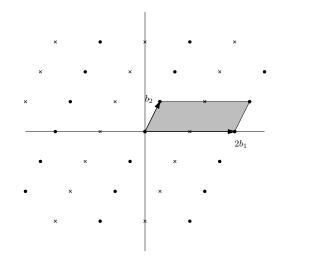
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• It expresses the *density* of a lattice.

A Sublattice



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It transforms b_i to

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• For all $i \neq j \langle \tilde{b}_i, \tilde{b}_j \rangle = 0$.

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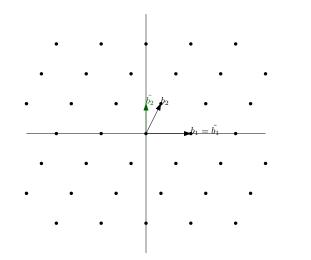
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The order of the input matters.

An example of GSO



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Gram Schmidt Orthogonormal Basis

Let $b_1,\ldots,b_n\in\mathbb{R}^m.$ If we normalize the GSO vectors we get an orthonormal basis

$$\frac{\tilde{b}_1}{\|\tilde{b}_1\|}, \dots, \frac{\tilde{b}_n}{\|\tilde{b}_n\|}$$

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In this basis we have

$$B = \begin{bmatrix} \|\tilde{b_1}\| & \mu_{2,1}\|\tilde{b_1}\| & \dots & \mu_{n,1}\|\tilde{b_1}\| \\ 0 & \|\tilde{b_2}\| & \dots & \mu_{n,2}\|\tilde{b_2}\| \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \dots & 0 & \|\tilde{b_n}\| \\ 0 & \dots & 0 & 0 \\ \vdots & \ddots & \vdots & \vdots \\ 0 & \dots & 0 & 0 \end{bmatrix}$$

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From this we can easily get that $\det(\mathcal{L}(B)) = \prod_{i=1}^n \|\tilde{b}_i\|$

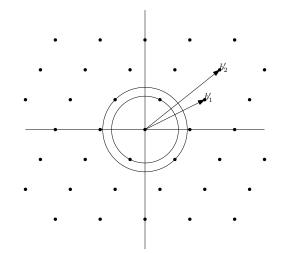
We define the *i*-th successive minima of Λ as the radius of the smallest ball that contains that contains *i* linearly independent lattice points. More formally

Definition

The *i*-th successive minima of Λ is

 $\lambda_i(\Lambda) = \inf\{r \mid \dim(\operatorname{span}(\Lambda \cap \overline{\mathbf{B}}(0, r))) > i\}$

Successive Minima Example



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Theorem

Let $\mathcal{L}(B)$ be a lattie and \tilde{B} its GSO. Then $\lambda_1(\mathcal{L}(B)) \ge \min_i \|\tilde{b}_i\| > 0$.

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- $|\langle Bx, \tilde{b}_j \rangle| = |\langle \sum_{i=1}^j b_i x_i, \tilde{b}_j \rangle| = |x_j| \|\tilde{b}_j\|^2$

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- We also have $|\langle Bx, \tilde{b_j} \rangle| \le \|Bx\| \cdot \|\tilde{b_j}\|.$

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Theorem

Let $\mathcal{L}(B)$ be a lattie and \tilde{B} its GSO. Then $\lambda_1(\mathcal{L}(B)) \ge \min_i \|\tilde{b_i}\| > 0$.

Proof.

- Suppose $x \in \mathbb{Z}^n$ and $Bx \in \mathcal{L}(B)$.
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Lattices are discrete structures.

Theorem

For any full rank lattice Λ and any measurable $S \subseteq \mathbb{R}^n$ with $vol(S) > det(\Lambda)$, there exist $z_1, z_2 \in S$ such that $z_1 - z_2 \in \Lambda$.

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- By the previous theorem, there exist $z_1, z_2 \in S'$ such that $z_1 z_2 \in \Lambda$.

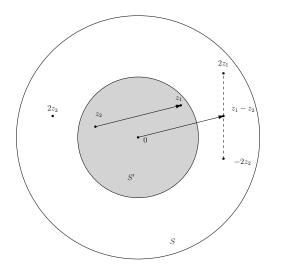
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• We have $2z_1, -2z_2 \in S$ and we get $z_1 - z_2 \in S$



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Bounding Successive Minima

By selecting appropriate sets (ball and ellipsoid respectively) we can deduce the following upper bounds for the succesive minima using the previous theorem.

$$\lambda_1(\Lambda) \leq \sqrt{n} \cdot \det(\Lambda)^{rac{1}{n}} \ (\prod_{i=1}^n \lambda_i(\Lambda))^{rac{1}{n}} \leq \sqrt{n} \cdot \det(\Lambda)^{rac{1}{n}}$$

Algebraic lattice points are easy:

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• Membership: Given a matrix B and a point x decide wheather $x \in \mathcal{L}(B)$.

Equivalence: Given matrices B, D decide wheather $\mathcal{L}(B) = \mathcal{L}(D)$. Things get harder when geometry comes to play.

Shortest Vector Problem

• SearchSVP_{γ}: Given $B \in \mathbb{Z}^{m \times n}$ find $v \in \mathcal{L}(B)$ such that $v \neq 0$ and $||v|| \leq \gamma \cdot \lambda_1(\mathcal{L}(B))$.

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• **OptimizationSVP**_{γ}: Given $B \in \mathbb{Z}^{m \times n}$ find d such that $d \leq \lambda_1(\mathcal{L}(B)) \leq \gamma \cdot d$.

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For $\gamma=1$ we get the exact versions of these problems. These are computationally equivalent.

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For the general case it is an open problem if this holds.

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1 Lattices in \mathbb{R}^m

2 The LLL Algorithm

3 Babai's Nearest Plane Algorithm

4 Complexity Results

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- Used for many problems, namely many algebraic problems, combinatorial optimization, cryptanalisis.

Definition

A basis $B = [b_1 \ b_2 \ \dots \ b_n]$ is a δ -LLL reduced basis if

1 forall $i \in [n]$, j < i it holds that $|\mu_{i,j}| \le \frac{1}{2}$

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• LLL produces a δ -LLL reduced basis.

Consider the orthonormal basis produced by GSO. A $\delta-\rm LLL$ reduced basis looks like this

$$\begin{bmatrix} \|\tilde{b}_1 &\leq \frac{1}{2}\|\tilde{b}_1\| & \cdots &\leq \frac{1}{2}\|\tilde{b}_1\| \\ 0 & \|\tilde{b}_2\| & \cdots &\leq \frac{1}{2}\|\tilde{b}_2\| \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots &\leq \frac{1}{2}\|\tilde{b}_{n-1}\| \\ 0 & 0 & \cdots & \|\tilde{b}_n\| \end{bmatrix}$$

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Theorem

Suppose b_1, \ldots, b_n is a δ -LLL reduced basis. Then

$$\|b_1\| \leq \Big(rac{2}{\sqrt{4\delta-1}}\Big)^{n-1}\lambda_1(\mathcal{L}(B))$$

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Proof.

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For $\delta = \frac{3}{4}$ this gives a $2^{\frac{n-1}{2}}$ approximation ratio.

1 Start Compute $\tilde{b_1}, \ldots, \tilde{b_n}$ 2 Reduction for i = 2 to nfor j = i - 1 to 1 $c_{i,j} = \lfloor \frac{\langle b_i, \tilde{b}_j \rangle}{\langle \tilde{b}_j, \tilde{b}_j \rangle} \rceil$ $b_i \leftarrow b_i - c_{i,j} b_j$ 3 Swap if there exists i s.t $\delta \|\tilde{b}_i\|^2 > \|\mu_{i+1,i}\tilde{b}_i + \tilde{b}_{i+1}\|^2$

 $b_i \leftrightarrow b_{i+1}$ **goto** start

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$$|\mu_{i,j}| = \left|\frac{\langle b_i - c_{i,j}b_j, \tilde{b}_j \rangle}{\langle \tilde{b}_j, \tilde{b}_j \rangle}\right| = \left|\frac{\langle b_i, \tilde{b}_j \rangle}{\langle \tilde{b}_j, \tilde{b}_j \rangle} - \lfloor\frac{\langle b_i, \tilde{b}_j \rangle}{\langle \tilde{b}_j, \tilde{b}_j \rangle}\right| \cdot \frac{\langle b_j, \tilde{b}_j \rangle}{\langle \tilde{b}_j, \tilde{b}_j \rangle}\right| \le \frac{1}{2}$$

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- Each iteration runs in polynomial time with respect to the input (not so simple).
- We need to show that the number of iterations is polynomial.

• We define $\mathcal{D}_{B,i} = \det \Lambda_i = \prod_{j=1}^i \|\tilde{b_1}\| \cdots \|\tilde{b_j}\|$

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- Initially the size of \mathcal{D}_B is polynomial. This is because

$$\mathcal{D}_B = \prod_{i=1}^n \|\tilde{b_1}\| \cdots \|\tilde{b_i}\| = \|b_1\|^n \|b_2\|^{n-1} \cdots \|b_n\| \le \max_i \|b_i\|^{rac{n(n+1)}{2}}$$

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• We will show that \mathcal{D}_B decreases by a constant factor in each iteration.

Introduction to Lattices

Bounding iterations of LLL

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. In particular

$$\begin{split} \frac{\mathcal{D}'_{B,i}}{\mathcal{D}_{B,i}} &= \frac{\det(\mathcal{L}(b_1, \dots, b_{i-1}, b_{i+1}))}{\det(\mathcal{L}(b_1, \dots, b_i))} \\ &= \frac{(\prod_{j=1}^{i-1} \|\tilde{b}_j\|) \|\mu_{i+1,i}\tilde{b}_i + \tilde{b}_{i+1}\|}{\prod_{j=1}^i \|\tilde{b}_j\|} \quad = \frac{\|\tilde{b}_j\| \cdot \|\mu_{i+1,i}\tilde{b}_i + \tilde{b}_{i+1}\|}{\|\tilde{b}_i\|} \leq \sqrt{\delta} \end{split}$$

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So we can have at most $\log_{\frac{1}{\sqrt{\delta}}} \mathcal{D}_B$ iteration which is polynomial.

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2 The LLL Algorithm

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4 Complexity Results

Introduction to Lattices Babai's Nearest Plane Algorithm

Babai's Nearest Plane Algorithm

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- Utilizes an LLL basis to solve SeacrhCVP.
- We will present the algorithm and omit its analysis.

The Nearest Plane Algorithm

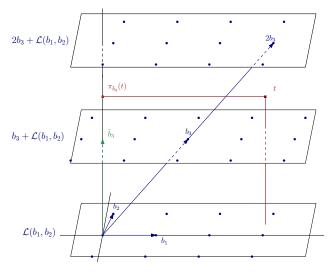
• Compute a δ -LLL reduced basis.

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$$b \leftarrow t$$

for $j = n$ to 1
 $c_j = \lfloor \frac{\langle b, \tilde{b}_j \rangle}{\langle \tilde{b}_j, \tilde{b}_j \rangle} \rfloor$
 $b \leftarrow b - c_j b_j$

Geometric Illustration of the Algorithm



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We show that **SubsetSum** reduces to **PromiseCVP**₁.

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We show that **SubsetSum** reduces to **PromiseCVP**₁. We map an instance of Subset Sum as follows

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We show that **SubsetSum** reduces to $\mathsf{PromiseCVP}_1$. We map an instance of Subset Sum as follows

$$\langle \{a_1,\ldots,a_n\},S\rangle \mapsto \left\langle B = \begin{bmatrix} a_1 & a_2 & \cdots & a_n \\ 2 & 0 & \cdots & 0 \\ 0 & 2 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & 2 \end{bmatrix}, \ t = \begin{bmatrix} S \\ 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}, \ r = \sqrt{n} \right\rangle$$

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If $\{\{a_1, \ldots, a_n\}, S\} \in$ SubsetSum then suppose that $\sum_{i \in A} a_i = S$. Now take y = Bz where z is vector with its j-th coordinate equal to 1 if $j \in A$ and 0 otherwise. Then $||Bz - t|| = ||[0 \pm 1 \ldots \pm 1]^T|| = \sqrt{n}$ and so $\langle B, t, r \rangle \in$ PromiseCVP₁.

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- If ⟨B, t, r⟩ ∈ PromiseCVP₁. Assume x ∈ L(B) such that ||x − t|| ≤ √n The last n coordinates are even, so subtracting 1 gives at least √n. It must be the case that the first coordinate is S.

We will show that we can solve the search problem given an oracle for the decisional problem.

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- Note that if we find the closest vector to t + v for $v \in \mathcal{L}$ we are done.

We iteratively make sparser the lattice while maintaining three properties

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the new subblatice or the shifted sublattice is r.

We perform the iterative step k = n + log r times for each coordinates.

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From there we can construct *t* for the initial lattice.

- We perform the iterative step k = n + log r times for each coordinates.
- Finally the basis of the lattice is of the form $B^* = [2^k b_1 \dots 2^k b_n]$.
- We know that $dist(B^*, t^*) = r$.
- Note that $\lambda_1(\mathcal{L}(B^*)) \geq 2^k = 2^n \cdot r$.
- The second closest vector to t^* is at distance at least $2^n r r \ge 2^{n-1} \cdot r$.
- So if we run the nearest plane algorithm we get the closest vector.
- From there we can construct *t* for the initial lattice.

We dont know how to generalize this for the gap versions of the problems.



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- So in the reduction, we delete a set of lattice points.

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- If any returns YES we return YES otherwise we return NO.

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We examine the two cases



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if (B, r) ∉ PromiseSVP_γ then λ₁(L(B)) > γ ⋅ r. So any lattice vector v has length ||v|| > γ ⋅ r. Now suppose that for some i the oracle returned YES. Then there exists v ∈ L(B_i) s.t. ||v − b_i|| ≤ r. But this is a lattice point in L(B) which is a contradiction.

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- if $(B, r) \in \mathbf{PromiseSVP}_{\gamma}$ then $\lambda_1(\mathcal{L}(B)) \leq r$. Let v be the smallest vector. Then $v = a_1b_1 + \ldots + a_nb_n$ for some a_i odd. Then $b_i + v \in \mathcal{L}(B_i)$ and its distance from b_i is less than r so the oracle must return YES.

The end!

Thank you! Questions?

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